

Encoding Timed Models as Uniform Labeled Transition Systems [★]

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Abstract. We provide a unifying view of timed models such as timed automata, probabilistic timed automata, and Markov automata. The timed models and their bisimulation semantics are encoded in the framework of uniform labeled transition systems. In this unifying framework, we show that the timed bisimilarities present in the literature can be re-obtained and that a new bisimilarity, of which we exhibit the modal logic characterization, can be introduced for timed models including probabilities. We finally highlight similarities and differences among the models.

1 Introduction

Several extensions of classical automata have been proposed in the last twenty years to model timed aspects of the behavior of systems and to support the verification of hard and soft real-time constraints. The first of these extensions is given by timed automata (TA) [1]. They are equipped with clock variables that measure the passage of time within states, while transitions are instantaneous, may be subject to clock-based guards, and may reset the value of some clocks.

A subsequent extension is that of probabilistic timed automata (PTA) [12]. They are TA where the destination of every transition is a function that associates with each state the probability of being the target state. This allows for the representation both of nondeterministic choices and of probabilistic choices, and enables the investigation of properties such as the probability of executing certain activities within a given deadline is not lower than a given threshold.

The semantics of a TA/PTA can be defined in terms of a variant of labeled transition system (LTS) [11] together with a notion of bisimulation [8]. The characteristic of the underlying variant of LTS is that of having uncountably many states, as any of these states essentially corresponds to a pair composed of a TA/PTA state and a vector of clock values each taken from $\mathbb{R}_{\geq 0}$.

A more recent extension is constituted by Markov automata (MA) [7], in which the probabilistic flavor of PTA transitions is retained, while temporal aspects are described through exponentially distributed random variables rather than deterministic quantities. Since exponential distributions enjoy the memoryless property, an MA no longer needs clocks and hence can be directly viewed as a variant of LTS whose states correspond to the MA states.

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In order to emphasize similarities and differences among the various models, in this paper we provide a unifying view of TA, PTA, and MA by encoding all of them as uniform labeled transition systems (ULTRAS) [4]. This is a recently developed framework that has proven to be well suited for uniformly representing different models – ranging from LTS models to discrete-/continuous-time Markov chains and Markov decision processes without/with internal nondeterminism – together with their behavioral equivalences.

The paper is organized as follows. In Sect. 2, we recall the notion of ULTRAS and we extend it in order to deal with uncountable state spaces. In Sect. 3, we encode as ULTRAS the variant of LTS underlying TA and we show that the corresponding bisimilarity in [16, 20] coincides with a suitable instance of the bisimilarity for ULTRAS. In Sect. 4, we reuse the same encoding to handle TA. In Sect. 5, we encode as ULTRAS the variant of LTS underlying PTA and we show that two different bisimilarities can be defined: the one in [19] and a new one for which we exhibit a modal logic characterization. In Sects. 6 and 7, we reuse almost the same encoding to handle PTA and MA, respectively. Finally, in Sect. 8 we draw some conclusions about the considered timed models.

2 Revisiting the Definition of ULTRAS

The definition of ULTRAS given in [4] was based on a set of states and a set of transition-labeling actions that are at most countable. When dealing with TA and PTA models whose time domain is $\mathbb{R}_{\geq 0}$, the underlying LTS models turn out to have *uncountably* many states and actions. Therefore, we need to extend the definition of ULTRAS by admitting uncountable sets of states and actions, in a way that preserves the results in [4].

Every ULTRAS is parameterized with respect to a set D , whose values are interpreted as different degrees of *one-step reachability*, and a preorder \sqsubseteq_D equipped with minimum \perp_D , which denotes *unreachability*. In this paper, we consider the set $[S \rightarrow D]_{cs}$ of *countable-support* functions from a set S to D , i.e., the set of functions $\mathcal{D} : S \rightarrow D$ whose support $supp(\mathcal{D}) = \{s \in S \mid \mathcal{D}(s) \neq \perp_D\}$ is at most countable. As in [4], when S is a set of states, every element \mathcal{D} of $[S \rightarrow D]_{cs}$ is interpreted as a *next-state distribution function* and $supp(\mathcal{D})$ represents the set of reachable states.

Definition 1. *Let $(D, \sqsubseteq_D, \perp_D)$ be a preordered set equipped with a minimum. A uniform labeled transition system on $(D, \sqsubseteq_D, \perp_D)$, or D -ULTRAS for short, is a triple $\mathcal{U} = (S, A, \longrightarrow)$ where S is a possibly uncountable set of states, A is a possibly uncountable set of actions, and $\longrightarrow \subseteq S \times A \times [S \rightarrow D]_{cs}$ is a transition relation. We say that the D -ULTRAS \mathcal{U} is functional iff \longrightarrow is a total function from $S \times A$ to $[S \rightarrow D]_{cs}$. ■*

Every transition (s, a, \mathcal{D}) is written $s \xrightarrow{a} \mathcal{D}$, where $\mathcal{D}(s')$ is a D -value quantifying the degree of reachability of s' from s via that transition and $\mathcal{D}(s') = \perp_D$ means that s' is not reachable with that transition. If the D -ULTRAS is functional, we shall write $\mathcal{D}_{s,a}(s')$ to denote the same D -value.

A D -ULTRAS can be depicted as a directed graph-like structure in which vertices represent states and action-labeled edges represent action-labeled transitions. Given a transition $s \xrightarrow{a} \mathcal{D}$, the corresponding a -labeled edge goes from the vertex representing s to a set of vertices linked by a dashed line, each of which represents a state $s' \in \text{supp}(\mathcal{D})$ and is labeled with $\mathcal{D}(s')$. Should $\mathcal{D}(s') = \perp_D$ for all states s' – which may happen when the considered D -ULTRAS is functional – the transition would not be depicted at all. A \mathbb{B} -ULTRAS is shown on the right-hand side of Fig. 1, where $\mathbb{B} = \{\perp, \top\}$ is the support set of the Boolean algebra, \perp (false) denotes unreachability, \top (true) denotes reachability, and $\perp \sqsubseteq_{\mathbb{B}} \top$.

In [4], various equivalences were defined over ULTRAS and shown to coincide in most cases with those appeared in the literature of nondeterministic, probabilistic, stochastic, and mixed models. Since in this paper we focus on bisimilarity, we shall recall only the definition of bisimilarity for ULTRAS. This definition, like the one of the other equivalences, is parameterized with respect to a measure function that expresses the degree of *multi-step reachability* of a set of states in terms of values taken from a preordered set equipped with minimum. In the following, we call *trace* an element α of A^* and we denote by ε the empty trace, by “ $|\cdot|$ ” the operation that computes the length of a trace, and by “ $_ \circ _$ ” the operation that concatenates two traces.

Definition 2. Let $\mathcal{U} = (S, A, \longrightarrow)$ be a D -ULTRAS, $n \in \mathbb{N}$, $s_i \in S$ for $0 \leq i \leq n$, and $a_i \in A$ for $1 \leq i \leq n$. We say that $s_0 \xrightarrow{a_1} s_1 \xrightarrow{a_2} s_2 \dots s_{n-1} \xrightarrow{a_n} s_n$ is a computation of \mathcal{U} of length n that goes from s_0 to s_n and is labeled with trace $a_1 a_2 \dots a_n$ iff for all $i = 1, \dots, n$ there exists a transition $s_{i-1} \xrightarrow{a_i} \mathcal{D}_i$ such that $s_i \in \text{supp}(\mathcal{D}_i)$. ■

Definition 3. Let $\mathcal{U} = (S, A, \longrightarrow)$ be a D -ULTRAS and $(M, \sqsubseteq_M, \perp_M)$ be a preordered set equipped with a minimum. A measure function on $(M, \sqsubseteq_M, \perp_M)$ for \mathcal{U} , or M -measure function for \mathcal{U} , is a function $\mathcal{M}_M : S \times A^* \times 2^S \rightarrow M$ such that the value of $\mathcal{M}_M(s, \alpha, S')$ is defined by induction on $|\alpha|$ and depends only on the reachability of a state in S' from state s through computations labeled with trace α . ■

Definition 4. Let $\mathcal{U} = (S, A, \longrightarrow)$ be a D -ULTRAS and \mathcal{M}_M be an M -measure function for \mathcal{U} . An equivalence relation \mathcal{B} over S is an \mathcal{M}_M -bisimulation iff, whenever $(s_1, s_2) \in \mathcal{B}$, then for all actions $a \in A$ and groups of equivalence classes $\mathcal{G} \in 2^{S/\mathcal{B}}$ it holds that:

$$\mathcal{M}_M(s_1, a, \bigcup \mathcal{G}) = \mathcal{M}_M(s_2, a, \bigcup \mathcal{G})$$

where $\bigcup \mathcal{G}$ is the union of all the equivalence classes in \mathcal{G} . We say that $s_1, s_2 \in S$ are \mathcal{M}_M -bisimilar, written $s_1 \sim_{\mathcal{B}, \mathcal{M}_M} s_2$, iff there exists an \mathcal{M}_M -bisimulation \mathcal{B} over S such that $(s_1, s_2) \in \mathcal{B}$. ■

The preordered structure $(M, \sqsubseteq_M, \perp_M)$ for multi-step reachability used in the definition of the equivalence does *not* necessarily coincide with the preordered structure $(D, \sqsubseteq_D, \perp_D)$ for one-step reachability used in the definition of the model. In [4], various cases were illustrated that demonstrate the necessity of keeping the two structures separate to retrieve certain equivalences.

The definition of bisimilarity is given in the style of [14], i.e., it requires a bisimulation to be an equivalence relation. However, it deals with arbitrary *groups of equivalence classes* rather than only with individual equivalence classes. As shown in [4], working with groups of equivalence classes provides an adequate support to models in which nondeterminism and quantitative aspects coexist. In particular, it gives rise to new probabilistic bisimulation equivalences that have interesting logical characterizations (see the references in [4]).

3 Encoding Timed LTS Models

Timed processes can be represented as models enriched with timing information. Following the orthogonal-time approach¹ of [16], we consider an extension of LTS called timed labeled transition system (TLTS). In this model, functional aspects (i.e., process activities assumed to be instantaneous) are separate from temporal aspects (i.e., time passing) by means of two distinct transition relations: one labeled with actions and the other labeled with amounts of time. Since we are interested in TLTS models obtained from TA, we shall consider $\mathbb{R}_{\geq 0}$ as time domain and allow for uncountably many states and actions.

Definition 5. A timed labeled transition system (TLTS) is a quadruple $(S, A, \longrightarrow, \rightsquigarrow)$ where S is a possibly uncountable set of states, A is a possibly uncountable set of actions, and:

- $\longrightarrow \subseteq S \times A \times S$ is an action-transition relation such that for all $s \in S$ and $a \in A$ it holds that $\{s' \in S \mid (s, a, s') \in \longrightarrow\}$ is at most countable.
- $\rightsquigarrow \subseteq S \times \mathbb{R}_{\geq 0} \times S$ is a time-transition relation satisfying $(s, 0, s) \in \rightsquigarrow$ [0-delay], $(s, t, s'_1) \in \rightsquigarrow \wedge (s, t, s'_2) \in \rightsquigarrow \implies s'_1 = s'_2$ [time determinism], and $(s, t_1, s') \in \rightsquigarrow \wedge (s', t_2, s'') \in \rightsquigarrow \implies (s, t_1 + t_2, s'') \in \rightsquigarrow$ [time additivity]. ■

Every action-transition (s, a, s') is written $s \xrightarrow{a} s'$ and means that s can reach s' by executing action a , whilst every time-transition (s, t, s') is written $s \xrightarrow{t} s'$ and means that s can evolve into s' after an amount of time equal to t .

Following [20], we can merge the two transition relations into a single one by adding a special time-elapsing action $\epsilon(t)$ for every $t \in \mathbb{R}_{\geq 0}$. With this in mind, it is immediate to see that a TLTS can be encoded as a functional \mathbb{B} -ULTRAS.

Definition 6. Let $(S, A, \longrightarrow, \rightsquigarrow)$ be a TLTS. Its corresponding functional \mathbb{B} -ULTRAS $\mathcal{U} = (S, A_{\mathcal{U}}, \longrightarrow_{\mathcal{U}})$ is defined by letting:

- $A_{\mathcal{U}} = A \cup \{\epsilon(t) \mid t \in \mathbb{R}_{\geq 0}\}$.
- $s \xrightarrow{a}_{\mathcal{U}} \mathcal{D}_{s,a}$ for all $s \in S$ and $a \in A_{\mathcal{U}}$.
- $\mathcal{D}_{s,a}(s') = \begin{cases} \top & \text{if } a \in A \text{ and } s \xrightarrow{a} s', \text{ or } a = \epsilon(t) \text{ and } s \xrightarrow{t} s' \\ \perp & \text{otherwise} \end{cases}$
for all $s' \in S$. ■

¹ As opposed to the integrated-time approach, in which process activities are assumed to be durational: see [6, 3] for an overview of both approaches in different settings.

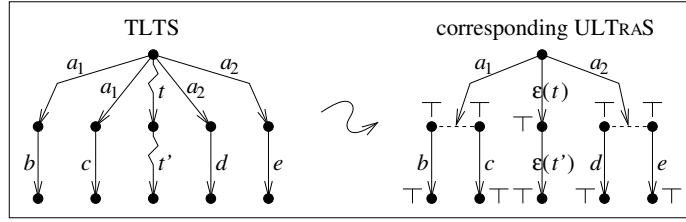


Fig. 1. Translation of a TLTS exhibiting both external and internal nondeterminism

If a TLTS state has a certain number of *differently labeled* outgoing action-transitions, then those transitions are retained in the corresponding functional \mathbb{B} -ULTRAS. In other words, *external nondeterminism* in the original model is preserved by the resulting model. In contrast, *internal nondeterminism* is encoded within the target countable-support functions of the transitions of the resulting model. Indeed, if a TLTS state has several *identically labeled* outgoing action-transitions, then a single transition is generated in the corresponding functional \mathbb{B} -ULTRAS, in which several states are assigned \top as reachability value. The encoding of both forms of nondeterminism is exemplified in Fig. 1.

A notion of bisimilarity for timed processes was introduced in [16, 20], where the congruence property and an equational characterization were also studied. The decidability of timed bisimilarity was established in [5].

Definition 7. Let $(S, A, \xrightarrow{\cdot}, \rightsquigarrow)$ be a TLTS. A relation \mathcal{B} over S is a timed bisimulation iff, whenever $(s_1, s_2) \in \mathcal{B}$, then for all actions $a \in A$ and amounts of time $t \in \mathbb{R}_{\geq 0}$ it holds that:

- For each $s_1 \xrightarrow{a} s'_1$ (resp. $s_2 \xrightarrow{a} s'_2$) there exists $s_2 \xrightarrow{a} s'_2$ (resp. $s_1 \xrightarrow{a} s'_1$) such that $(s'_1, s'_2) \in \mathcal{B}$.
- For each $s_1 \rightsquigarrow^t s'_1$ (resp. $s_2 \rightsquigarrow^t s'_2$) there exists $s_2 \rightsquigarrow^t s'_2$ (resp. $s_1 \rightsquigarrow^t s'_1$) such that $(s'_1, s'_2) \in \mathcal{B}$.

We say that $s_1, s_2 \in S$ are timed bisimilar, written $s_1 \sim_{\text{TB}} s_2$, iff there exists a timed bisimulation \mathcal{B} over S such that $(s_1, s_2) \in \mathcal{B}$. ■

Timed bisimilarity over TLTS models is captured by $\sim_{\mathbb{B}, \mathcal{M}_{\mathbb{B}}}$ over the corresponding functional \mathbb{B} -ULTRAS models, where measure function $\mathcal{M}_{\mathbb{B}}$ is defined in Table 1. When $\alpha = a \circ \alpha'$, the measure function considers each possible next state s' by examining whether it is reachable from s via a ($\mathcal{D}_{s,a}(s')$) and it can reach a state in S' via α' ($\mathcal{M}_{\mathbb{B}}(s', \alpha', S')$). If this is the case for at least one of the possible next states s' , then $\mathcal{M}_{\mathbb{B}}(s, \alpha, S') = \top$, otherwise $\mathcal{M}_{\mathbb{B}}(s, \alpha, S') = \perp$. Note that, for TLTS models, the preordered structure of the corresponding ULTRAS models coincides with the preordered structure of the measure function.

Theorem 1. Let $(S, A, \xrightarrow{\cdot}, \rightsquigarrow)$ be a TLTS and $\mathcal{U} = (S, A_{\mathcal{U}}, \xrightarrow{\cdot}_{\mathcal{U}})$ be the corresponding functional \mathbb{B} -ULTRAS. For all $s_1, s_2 \in S$:

$$s_1 \sim_{\text{TB}} s_2 \iff s_1 \sim_{\mathbb{B}, \mathcal{M}_{\mathbb{B}}} s_2 \quad \blacksquare$$

$$\mathcal{M}_{\mathbb{B}}(s, \alpha, S') = \begin{cases} \bigvee_{s' \in S} \mathcal{D}_{s,a}(s') \wedge \mathcal{M}_{\mathbb{B}}(s', \alpha', S') & \text{if } \alpha = a \circ \alpha' \\ \top & \text{if } \alpha = \varepsilon \text{ and } s \in S' \\ \perp & \text{if } \alpha = \varepsilon \text{ and } s \notin S' \end{cases}$$

Table 1. Measure function for functional \mathbb{B} -ULTRAS models representing TLTS models

4 Encoding Timed Automata

Timed automata (TA) [1] extend classical automata by introducing *clock variables*, or simply clocks, that measure the passage of time. They all advance at the same speed and take values in $\mathbb{R}_{\geq 0}$. A *clock valuation* $\nu \in \mathcal{V}_{\mathcal{X}}$ over a finite set of clocks \mathcal{X} is a total function from \mathcal{X} to $\mathbb{R}_{\geq 0}$. Given a valuation ν and a delay $t \in \mathbb{R}_{\geq 0}$, we let $\nu + t$ denote the valuation mapping each clock $x \in \mathcal{X}$ into $\nu(x) + t$. A *reset* γ is a set of clocks in \mathcal{X} whose value is set back to zero. For a valuation ν and a reset γ , we let $\nu \setminus \gamma(x) = 0$ if $x \in \gamma$ and $\nu \setminus \gamma(x) = \nu(x)$ if $x \notin \gamma$.

In TA, time elapses in states, called *locations*, as long as *invariant conditions* associated with the locations themselves hold. These are constraints on the values of the clocks through which notions such as urgency or laziness of actions can be expressed [9]. In contrast, the execution of an action transition is considered instantaneous. Transitions are *guarded*, i.e., enabled/disabled, by constraints on the values of the clocks, and can reset the value of some clocks.

The set $\Psi_{\mathcal{X}}$ of *clock constraints* over a finite set of clocks \mathcal{X} is defined by the following grammar: $\psi ::= x \# c \mid \psi \wedge \psi$ where $x \in \mathcal{X}$, $c \in \mathbb{N}$, and $\# \in \{<, >, \leq, \geq, =\}$. Clock constraints are assessed over clock valuations. The satisfaction of a clock constraint ψ by a valuation ν , denoted by $\nu \models \psi$, is defined as follows: (i) $\nu \models x \# c$ iff $\nu(x) \# c$, (ii) $\nu \models \psi_1 \wedge \psi_2$ iff $\nu \models \psi_1$ and $\nu \models \psi_2$. The given syntax for constraints is minimal; the so-called diagonal clock constraints of the form $x - y \# c$ can be simulated by using more locations and the constraints of the given form [2]. An invariant condition is a clock constraint with the property of being *past-closed*, i.e., for all valuations ν and delays $t \in \mathbb{R}_{\geq 0}$ it holds that $\nu + t \models \psi \implies \nu \models \psi$.

Definition 8. A timed automaton (TA) is a tuple $(L, A, \mathcal{X}, I, \longrightarrow)$ where L is a finite set of locations, A is a set of actions, \mathcal{X} is a finite set of clocks, I is a function mapping each location into an invariant condition, and $\longrightarrow \subseteq L \times \Psi_{\mathcal{X}} \times A \times 2^{\mathcal{X}} \times L$ is a transition relation. ■

Every transition is written $\ell \xrightarrow{\psi, a, \gamma} \ell'$ where ℓ is the source location, ψ is the guard, a is the action label, γ is the clock reset, and ℓ' is the target location.

The semantics of a TA is given in terms of a TLTS. Thus, it is natural to encode a TA as a functional \mathbb{B} -ULTRAS generated by using the same conditions defining the TA semantics.

Definition 9. Let $(L, A, \mathcal{X}, I, \longrightarrow)$ be a TA. Its corresponding functional \mathbb{B} -ULTRAS $\mathcal{U} = (S, A_{\mathcal{U}}, \longrightarrow_{\mathcal{U}})$ is defined by letting:

- $S = \{(\ell, \nu) \in L \times \mathcal{V}_X \mid \nu \models I(\ell)\}$.
 - $A_{\mathcal{U}} = A \cup \{\epsilon(t) \mid t \in \mathbb{R}_{\geq 0}\}$.
 - $(\ell, \nu) \xrightarrow{a}_{\mathcal{U}} \mathcal{D}_{(\ell, \nu), a}$ for all $(\ell, \nu) \in S$ and $a \in A_{\mathcal{U}}$.
 - $\mathcal{D}_{(\ell, \nu), a}(\ell', \nu') = \begin{cases} \top & \text{if } a \in A, \ell \xrightarrow{\psi, a, \gamma} \ell', \nu \models \psi, \nu' = \nu \setminus \gamma, \nu' \models I(\ell') \\ \top & \text{if } a = \epsilon(t), \ell' = \ell, \nu' = \nu + t, \nu' \models I(\ell') \\ \perp & \text{otherwise} \end{cases}$
- for all $(\ell', \nu') \in S$. ■

Timed bisimilarity over TA models is defined in terms of the underlying TLTS models. Therefore, we can reuse both Def. 7 and Table 1, so that Thm. 1 also applies to functional \mathbb{B} -ULTRAS models corresponding to TA models.

5 Encoding Probabilistic Timed LTS Models

A probabilistic extension of the TLTS model (PTLTS) was introduced in [19]. Following the simple probabilistic automaton model of [18], the action-transition relation is transformed into a probabilistic action-transition relation. This means that a PTLTS action transition, instead of leading to a single target state, has a *probability distribution over target states* assigning each such state the probability of being reached. Therefore, the choice among several outgoing action transitions from the same state is *nondeterministic*, whereas the choice of the target state for the selected transition is *probabilistic*. Given a possibly uncountable set S , we denote by $\text{Distr}_{\text{cs}}(S)$ the set of probability distributions \mathcal{D} over S whose support $\text{supp}(\mathcal{D}) = \{s \in S \mid \mathcal{D}(s) > 0\}$ is at most countable.

While in [19] there is a single transition relation and hence each transition is also labeled with the duration of the corresponding action, here we stick to the orthogonal-time approach and hence keep using two transition relations: a probabilistic one labeled with actions and a deterministic one labeled with amounts of time. We prefer to do so for two reasons. Firstly, this allows us to use a consistent notation and model structure throughout the paper. Secondly, separating functional aspects from time aspects simplifies the development of weak behavioral equivalences, as has been shown in the deterministic time case [20, 17, 13] and in the stochastic time case [10, 7].

Definition 10. A probabilistic timed labeled transition system (PTLTS) is a quadruple $(S, A, \longrightarrow, \rightsquigarrow)$ where S is a possibly uncountable set of states, A is a possibly uncountable set of actions, and:

- $\longrightarrow \subseteq S \times A \times \text{Distr}_{\text{cs}}(S)$ is a probabilistic action-transition relation.
- $\rightsquigarrow \subseteq S \times \mathbb{R}_{\geq 0} \times S$ is a time-transition relation satisfying 0-delay, time determinism, and time additivity. ■

Every action-transition (s, a, \mathcal{D}) is written $s \xrightarrow{a} \mathcal{D}$ – which is already in the ULTRAS transition format – whilst every time-transition (s, t, s') is written $s \xrightarrow{t} s'$. As in the TLTS case, we can merge the two transition relations into a single one by adding a special time-elapsing action $\epsilon(t)$ for every $t \in \mathbb{R}_{\geq 0}$, such that

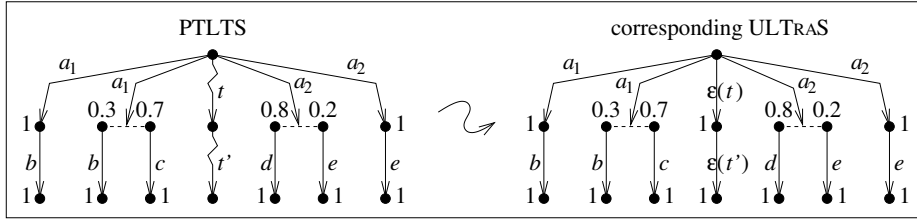


Fig. 2. Translation of a PTLTS exhibiting both external and internal nondeterminism

the target distributions of the transitions labeled with such actions concentrate all the probability mass into a single state. At this point, it is straightforward to encode a PTLTS as an $\mathbb{R}_{[0,1]}$ -ULTRAS, which relies on the usual ordering for real numbers – with 0 denoting unreachability – and is not necessarily functional due to the coexistence of probability and internal nondeterminism [4]. In the following, given $s \in S$ we denote by δ_s the Dirac distribution for s , where $\delta_s(s) = 1$ and $\delta_s(s') = 0$ for all $s' \in S \setminus \{s\}$.

Definition 11. Let $(S, A, \longrightarrow, \rightsquigarrow)$ be a PTLTS. Its corresponding $\mathbb{R}_{[0,1]}$ -ULTRAS $\mathcal{U} = (S, A_{\mathcal{U}}, \longrightarrow_{\mathcal{U}})$ is defined by letting:

- $A_{\mathcal{U}} = A \cup \{\epsilon(t) \mid t \in \mathbb{R}_{\geq 0}\}$.
- $s \xrightarrow{a}_{\mathcal{U}} \mathcal{D}$ for each $s \xrightarrow{a} \mathcal{D}$.
- $s \xrightarrow{\epsilon(t)}_{\mathcal{U}} \delta_{s'}$ for each $s \xrightarrow{t} s'$. ■

Different from the TLTS encoding, both external nondeterminism and internal nondeterminism in the original PTLTS are preserved in the corresponding $\mathbb{R}_{[0,1]}$ -ULTRAS. This is exemplified in Fig. 2.

A notion of bisimilarity for probabilistic timed processes was introduced in [19], where a modal logic characterization and a decision procedure were also studied. Below, we reformulate the definition in the orthogonal-time framework and we let $\mathcal{D}(C) = \sum_{s \in C} \mathcal{D}(s)$ for $\mathcal{D} \in \text{Distr}_{cs}(S)$ and $C \subseteq S$.

Definition 12. Let $(S, A, \longrightarrow, \rightsquigarrow)$ be a PTLTS. An equivalence relation \mathcal{B} over S is a probabilistic timed bisimulation iff, whenever $(s_1, s_2) \in \mathcal{B}$, then for all actions $a \in A$ and amounts of time $t \in \mathbb{R}_{\geq 0}$ it holds that:

- For each $s_1 \xrightarrow{a} \mathcal{D}_1$ there exists $s_2 \xrightarrow{a} \mathcal{D}_2$ such that for all equivalence classes $C \in S/\mathcal{B}$ it holds that $\mathcal{D}_1(C) = \mathcal{D}_2(C)$.
- For each $s_1 \xrightarrow{t} s'_1$ there exists $s_2 \xrightarrow{t} s'_2$ such that $(s'_1, s'_2) \in \mathcal{B}$.

We say that $s_1, s_2 \in S$ are probabilistic timed bisimilar, written $s_1 \sim_{\text{PTB}} s_2$, iff there exists a probabilistic timed bisimulation \mathcal{B} over S such that $(s_1, s_2) \in \mathcal{B}$. ■

It is relatively easy to see that the relation \sim_{PTB} coincides with the following bisimulation equivalence defined over $\mathbb{R}_{[0,1]}$ -ULTRAS models corresponding to

$$\mathcal{M}_{2^{\mathbb{R}_{[0,1]}}}(s, \alpha, S') = \begin{cases} \bigcup_{s \xrightarrow{a} \mathcal{D}} \left\{ \sum_{s' \in S'} \mathcal{D}(s') \cdot p_{s'} \mid p_{s'} \in \mathcal{M}_{2^{\mathbb{R}_{[0,1]}}}(s', \alpha', S') \right\} & \text{if } \alpha = a \circ \alpha' \text{ and there exists } s \xrightarrow{a} \mathcal{D} \\ \{1\} & \text{if } \alpha = \varepsilon \text{ and } s \in S' \\ \{0\} & \text{if } \alpha = a \circ \alpha' \text{ and there is no } s \xrightarrow{a} \mathcal{D} \\ & \text{or } \alpha = \varepsilon \text{ and } s \notin S' \end{cases}$$

Table 2. Measure function for $\mathbb{R}_{[0,1]}$ -ULTRAS models representing PTLTS models

PTLTS models. The equivalence below is called *group-distribution* bisimilarity because it compares *entire distributions* of reaching groups of equivalence classes. Given two related states, for each transition of one of the two states there must exist an equally labeled transition of the other state such that, *for every group of equivalence classes*, the two transitions have the same probability of reaching a state in that group. In other words, the two transitions must be *fully matching*, i.e., they must match with respect to all groups.

Definition 13. Let $\mathcal{U} = (S, A_{\mathcal{U}}, \xrightarrow{\mathcal{U}})$ be the $\mathbb{R}_{[0,1]}$ -ULTRAS corresponding to a PTLTS $(S, A, \xrightarrow{\quad}, \sim)$. An equivalence relation \mathcal{B} over S is a probabilistic timed group-distribution bisimulation iff, whenever $(s_1, s_2) \in \mathcal{B}$, then for all actions $a \in A_{\mathcal{U}}$ it holds that:

- For each $s_1 \xrightarrow{a} \mathcal{U} \mathcal{D}_1$ there exists $s_2 \xrightarrow{a} \mathcal{U} \mathcal{D}_2$ such that for all groups of equivalence classes $\mathcal{G} \in 2^{S/\mathcal{B}}$ it holds that $\mathcal{D}_1(\bigcup \mathcal{G}) = \mathcal{D}_2(\bigcup \mathcal{G})$.

We say that $s_1, s_2 \in S$ are probabilistic timed group-distribution bisimilar, written $s_1 \sim_{\text{PTB,dis}} s_2$, iff there exists a probabilistic timed group-distribution bisimulation \mathcal{B} over S such that $(s_1, s_2) \in \mathcal{B}$. ■

Theorem 2. Let $(S, A, \xrightarrow{\quad}, \sim)$ be a PTLTS and $\mathcal{U} = (S, A_{\mathcal{U}}, \xrightarrow{\mathcal{U}})$ be the corresponding $\mathbb{R}_{[0,1]}$ -ULTRAS. For all $s_1, s_2 \in S$:

$$s_1 \sim_{\text{PTB}} s_2 \iff s_1 \sim_{\text{PTB,dis}} s_2 \quad \blacksquare$$

The relation \sim_{PTB} over PTLTS models has been expressed as $\sim_{\text{PTB,dis}}$ in the ULTRAS setting, but cannot be captured by any instantiation of the general bisimilarity for ULTRAS given in Def. 4. In the case of probabilistic timed processes, a natural measure function is the one defined in Table 2. Denoting by $2^{\mathbb{R}_{[0,1]}}$ the set of *nonempty* subsets of $\mathbb{R}_{[0,1]}$, this measure function associates a suitable element of $2^{\mathbb{R}_{[0,1]}}$ with every triple composed of a source state s , a trace α , and a set of destination states S' . The set $\mathcal{M}_{2^{\mathbb{R}_{[0,1]}}}(s, \alpha, S')$ contains for each possible way of resolving nondeterminism the probability of performing a computation that is labeled with trace α and leads to a state in S' from state s . It is worth pointing out that, while the considered ULTRAS models are based on the preordered structure $(\mathbb{R}_{[0,1]}, \leq, 0)$, the measure function relies on the different preordered structure $(2^{\mathbb{R}_{[0,1]}}, \sqsubseteq, \{0\})$ where $R_1 \sqsubseteq R_2$ means $\inf R_1 \leq \inf R_2$ and $|R_1| \leq |R_2|$ (the latter condition ensures $\{0\}$ being the minimum).

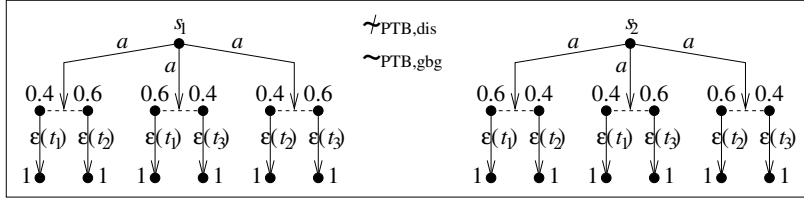


Fig. 3. Counterexample showing that $\sim_{\text{PTB,gbg}}$ is strictly coarser than $\sim_{\text{PTB,dis}}$

The resulting bisimilarity $\sim_{\mathcal{B}, \mathcal{M}_{2, \mathbb{R}_{[0,1]}}}$ captures the following equivalence that we call *group-by-group* bisimilarity because it considers *a single group of equivalence classes at a time*. Technically speaking, this amounts to anticipating the quantification over groups (underlined in Def. 13) with respect to the quantification over transitions. In this way, a transition departing from one of two related states is allowed to be matched, with respect to the probabilities of reaching different groups, by several different transitions departing from the other state. In other words, *partially matching* transitions are allowed.

Definition 14. Let $\mathcal{U} = (S, A_{\mathcal{U}}, \longrightarrow_{\mathcal{U}})$ be the $\mathbb{R}_{[0,1]}$ -ULTRAS corresponding to a PTLTS $(S, A, \longrightarrow, \rightsquigarrow)$. An equivalence relation \mathcal{B} over S is a probabilistic timed group-by-group bisimulation iff, whenever $(s_1, s_2) \in \mathcal{B}$, then for all actions $a \in A_{\mathcal{U}}$ and for all groups of equivalence classes $\mathcal{G} \in 2^{S/\mathcal{B}}$ it holds that:

- For each $s_1 \xrightarrow{a}_{\mathcal{U}} \mathcal{D}_1$ there exists $s_2 \xrightarrow{a}_{\mathcal{U}} \mathcal{D}_2$ such that $\mathcal{D}_1(\bigcup \mathcal{G}) = \mathcal{D}_2(\bigcup \mathcal{G})$.

We say that $s_1, s_2 \in S$ are probabilistic timed group-by-group bisimilar, written $s_1 \sim_{\text{PTB,gbg}} s_2$, iff there exists a probabilistic timed group-by-group bisimulation \mathcal{B} over S such that $(s_1, s_2) \in \mathcal{B}$. ■

Theorem 3. Let $\mathcal{U} = (S, A_{\mathcal{U}}, \longrightarrow_{\mathcal{U}})$ be the $\mathbb{R}_{[0,1]}$ -ULTRAS corresponding to a PTLTS $(S, A, \longrightarrow, \rightsquigarrow)$. For all $s_1, s_2 \in S$:

$$s_1 \sim_{\text{PTB,gbg}} s_2 \iff s_1 \sim_{\mathcal{B}, \mathcal{M}_{2, \mathbb{R}_{[0,1]}}} s_2 \quad \blacksquare$$

In presence of internal nondeterminism, $\sim_{\text{PTB,gbg}}$ strictly contains $\sim_{\text{PTB,dis}}$, as shown in Fig. 3. Indicating states with the actions they enable, it holds that $s_1 \not\sim_{\text{PTB,dis}} s_2$ because the group distribution of the leftmost a -transition of s_1 – which assigns probability 1 to each group containing both the $\epsilon(t_1)$ -state and the $\epsilon(t_2)$ -state, probability 0.4 to each group containing the $\epsilon(t_1)$ -state but not the $\epsilon(t_2)$ -state, probability 0.6 to each group containing the $\epsilon(t_2)$ -state but not the $\epsilon(t_1)$ -state, and probability 0 to any other group – is not matched by the group distribution of any of the three a -transitions of s_2 . In contrast, $s_1 \sim_{\text{PTB,gbg}} s_2$. For instance, the leftmost a -transition of s_1 is matched by the leftmost a -transition of s_2 with respect to every group containing both the $\epsilon(t_1)$ -state and the $\epsilon(t_2)$ -state, the central a -transition of s_2 with respect to every group containing the $\epsilon(t_1)$ -state but not the $\epsilon(t_2)$ -state, and the rightmost a -transition of s_2 with respect to every group containing the $\epsilon(t_2)$ -state but not the $\epsilon(t_1)$ -state.

Theorem 4. *Let $\mathcal{U} = (S, A_{\mathcal{U}}, \longrightarrow_{\mathcal{U}})$ be the $\mathbb{R}_{[0,1]}$ -ULTRAS corresponding to a PTLTS $(S, A, \longrightarrow, \rightsquigarrow)$. For all $s_1, s_2 \in S$:*

$$s_1 \sim_{\text{PTB,dis}} s_2 \implies s_1 \sim_{\text{PTB,gbg}} s_2 \quad \blacksquare$$

We conclude by exhibiting a modal logic characterization of $\sim_{\text{PTB,gbg}}$ (and hence of $\sim_{\text{B}, \mathcal{M}_{2^{\mathbb{R}_{[0,1]}}}}$). Unlike the characterization of \sim_{PTB} (i.e., $\sim_{\text{PTB,dis}}$) provided in [19], which relies on an expressive probabilistic extension of HML [8] interpreted over state distributions, here it is sufficient to consider the interval-based variant IPML of the probabilistic modal logic in [14] with the following syntax: $\phi ::= \text{true} \mid \neg\phi \mid \phi \wedge \phi \mid \langle a \rangle_{[p_1, p_2]} \phi$ where $a \in A_{\mathcal{U}}$ and $p_1, p_2 \in \mathbb{R}_{[0,1]}$ such that $p_1 \leq p_2$. A state $s \in S$ belongs to the set $\mathcal{M}[\langle a \rangle_{[p_1, p_2]} \phi]$ of states satisfying $\langle a \rangle_{[p_1, p_2]} \phi$ iff there exists $s \xrightarrow{a}_{\mathcal{U}} \mathcal{D}$ such that $p_1 \leq \mathcal{D}(\mathcal{M}[\phi]) \leq p_2$.

Theorem 5. *Let $\mathcal{U} = (S, A_{\mathcal{U}}, \longrightarrow_{\mathcal{U}})$ be the $\mathbb{R}_{[0,1]}$ -ULTRAS corresponding to a PTLTS $(S, A, \longrightarrow, \rightsquigarrow)$. For all $s_1, s_2 \in S$ it holds that $s_1 \sim_{\text{PTB,gbg}} s_2$ iff s_1 and s_2 satisfy the same formulae of IPML.* \blacksquare

6 Encoding Probabilistic Timed Automata

Probabilistic timed automata (PTA) [12] extend TA with probabilities. While the passage of time remains deterministic, the target of each action transition becomes a probability distribution. The approach is exactly the one described in Sect. 5 for moving from TLTS models to PTLTS models.

Definition 15. *A probabilistic timed automaton (PTA) is a tuple $(L, A, \mathcal{X}, I, \longrightarrow)$ where L is a finite set of locations, A is a set of actions, \mathcal{X} is a finite set of clocks, I is a function mapping each location into an invariant condition, and $\longrightarrow \subseteq L \times \Psi_{\mathcal{X}} \times A \times \text{Distr}_{\text{cs}}(2^{\mathcal{X}} \times L)$ is a transition relation.* \blacksquare

Every transition is written $\ell \xrightarrow{\psi, a} \mathcal{D}$ where \mathcal{D} is the probability distribution assigning each pair (γ, ℓ') the probability of being reached via that transition.

Like for TA, the semantics of a PTA is given in terms of a PTLTS. Following the same approach used in Sect. 4, we thus encode a PTA as an $\mathbb{R}_{[0,1]}$ -ULTRAS generated by using the same conditions defining the PTA semantics.

Definition 16. *Let $(L, A, \mathcal{X}, I, \longrightarrow)$ be a PTA. Its corresponding $\mathbb{R}_{[0,1]}$ -ULTRAS $\mathcal{U} = (S, A_{\mathcal{U}}, \longrightarrow_{\mathcal{U}})$ is defined by letting:*

- $S = \{(\ell, \nu) \in L \times \mathcal{V}_{\mathcal{X}} \mid \nu \models I(\ell)\}$.
- $A_{\mathcal{U}} = A \cup \{\epsilon(t) \mid t \in \mathbb{R}_{\geq 0}\}$.
- $(\ell, \nu) \xrightarrow{a}_{\mathcal{U}} \mathcal{D}$ for each $\ell \xrightarrow{\psi, a} \mathcal{D}'$ such that $\nu \models \psi$, where for all $(\ell', \nu') \in S$ $\mathcal{D}(\ell', \nu') = \sum_{\gamma \in \text{reset}(\nu, \nu')} \mathcal{D}'(\gamma, \ell')$ with $\text{reset}(\nu, \nu') = \{\gamma \in 2^{\mathcal{X}} \mid \nu \setminus \gamma = \nu'\}$.
- $(\ell, \nu) \xrightarrow{\epsilon(t)}_{\mathcal{U}} \delta_{(\ell', \nu')}$ for $\ell' = \ell$, $\nu' = \nu + t$, $\nu' \models I(\ell')$. \blacksquare

Similar to TA models, probabilistic timed bisimilarity over PTA models is defined in terms of the underlying PTLTS models. Therefore, we can reuse Defs. 12, 13, and 14 as well as Table 2, so that Thms. 2, 3, 4, and 5 also apply to $\mathbb{R}_{[0,1]}$ -ULTRAS corresponding to PTA models.

7 Encoding Markov Automata

So far, we have considered timed models in which temporal aspects are described as fixed amounts of time. In other words, in these models the passage of time is represented *deterministically*. However, in many situations there are fluctuations in the time that elapses between instantaneous activities. When these fluctuations are quantifiable, the passage of time can be represented *stochastically*.

Due to the simplicity of their mathematical treatment, *exponentially distributed random variables* are mostly used for a stochastic representation of time. Given one such variable X with parameter $\lambda \in \mathbb{R}_{>0}$, the probability that a duration sampled from X is at most $t \in \mathbb{R}_{\geq 0}$ is given by $\Pr\{X \leq t\} = 1 - e^{-\lambda \cdot t}$. The parameter λ is said the *rate* of X ; its reciprocal is the expected value of X .

If several alternative exponentially distributed delays can elapse from a state, the *race policy* is adopted; the delay that elapses is the one sampling the least duration. It can be shown that the following property \mathcal{RP} holds in that state: the sojourn time is exponentially distributed with rate given by the sum of the rates of the various delays, with the probability of selecting each such delay being proportional to its rate.

The recently introduced model of Markov automata (MA) [7] can be viewed as a variant of PTA models in which time passing is described through exponentially distributed random variables. An important property of any of these variables is that it enjoys the *memoryless property*; even if we know that a certain amount of time has already elapsed, the residual time is still quantified by the same exponentially distributed random variable. As a consequence, in this setting there is *no need for clocks* and hence Markov automata can actually be viewed as a variant of PTLTS models, with exponentially distributed delays (uniquely identified by their rates) in place of deterministic delays.

Definition 17. A Markov automaton (MA) is a quadruple $(S, A, \longrightarrow, \rightsquigarrow)$ where S is a possibly uncountable set of states, A is a possibly uncountable set of actions, and:

- $\longrightarrow \subseteq S \times A \times \text{Distr}_{\text{cs}}(S)$ is a probabilistic action-transition relation.
- $\rightsquigarrow \subseteq S \times \mathbb{R}_{>0} \times S$ is a bounded time-transition relation, i.e., for all $s \in S$ it holds that $\{s' \in S \mid \exists \lambda \in \mathbb{R}_{>0}. (s, \lambda, s') \in \rightsquigarrow\}$ is at most countable and $\sum_{(s, \lambda, s') \in \rightsquigarrow} \lambda < \infty$. ■

Similar to the PTLTS case, every action-transition (s, a, \mathcal{D}) is written $s \xrightarrow{a} \mathcal{D}$, every time-transition (s, λ, s') is written $s \xrightarrow{\lambda} s'$, and we can merge the two transition relations into a single one by adding a special time-elapsing action $\epsilon(\lambda)$ for every $\lambda \in \mathbb{R}_{>0}$. Following the transformation sketched in [7], it is straightforward to encode an MA as a not necessarily functional $\mathbb{R}_{[0,1]}$ -ULTRAS, in which the race policy is represented based on \mathcal{RP} . For each state having outgoing time-transitions, we generate a single time-elapsing transition – instead of one such transition for each original delay – such that its rate λ is the sum of the rates identifying the original delays and its target distribution assigns to every state a probability proportional to the rate at which that state can be reached.

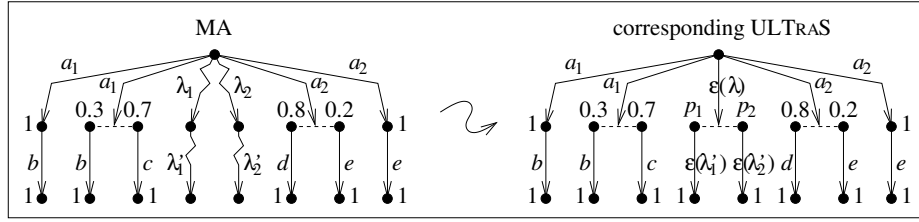


Fig. 4. Translation of an MA ($\lambda = \lambda_1 + \lambda_2$, $p_1 = \lambda_1/\lambda$, $p_2 = \lambda_2/\lambda$)

Definition 18. Let $(S, A, \longrightarrow, \rightsquigarrow)$ be an MA. Its corresponding $\mathbb{R}_{[0,1]}$ -ULTRAS $\mathcal{U} = (S, A_{\mathcal{U}}, \longrightarrow_{\mathcal{U}})$ is defined by letting:

- $A_{\mathcal{U}} = A \cup \{\epsilon(\lambda) \mid \lambda \in \mathbb{R}_{>0}\}$.
- $s \xrightarrow{a}_{\mathcal{U}} \mathcal{D}$ for each $s \xrightarrow{a} \mathcal{D}$.
- $s \xrightarrow{\epsilon(\lambda)}_{\mathcal{U}} \mathcal{D}$ for all $s \in S$ having outgoing time-transitions, where $\lambda = \sum_{s \rightsquigarrow s'} \lambda'$ and $\mathcal{D}(s') = \sum_{s \rightsquigarrow s'} \lambda' / \lambda$ for all $s' \in S$. ■

Nondeterministic choices over actions, probabilistic choices over states, and the race policy for exponentially distributed delays in the original MA are preserved in the corresponding $\mathbb{R}_{[0,1]}$ -ULTRAS. This is exemplified in Fig. 4.

A notion of bisimilarity for probabilistic exponentially-timed processes was introduced in [7]. Below, we reformulate the definition in terms of the two distinct transition relations.

Definition 19. Let $(S, A, \longrightarrow, \rightsquigarrow)$ be an MA. An equivalence relation \mathcal{B} over S is a probabilistic exponentially-timed bisimulation iff, whenever $(s_1, s_2) \in \mathcal{B}$, then for all actions $a \in A$ and rates $\lambda \in \mathbb{R}_{>0}$ it holds that:

- For each $s_1 \xrightarrow{a} \mathcal{D}_1$ there exists $s_2 \xrightarrow{a} \mathcal{D}_2$ such that for all equivalence classes $C \in S/\mathcal{B}$ it holds that $\mathcal{D}_1(C) = \mathcal{D}_2(C)$.
- If s_1 has outgoing time-transitions, then s_2 has outgoing time-transitions too and for all equivalence classes $C \in S/\mathcal{B}$ it holds that:

$$\sum_{s_1 \rightsquigarrow s'_1 \in C} \lambda = \sum_{s_2 \rightsquigarrow s'_2 \in C} \lambda$$

We say that $s_1, s_2 \in S$ are probabilistic exponentially-timed bisimilar, written $s_1 \sim_{\text{PEB}} s_2$, iff there exists a probabilistic exponentially-timed bisimulation \mathcal{B} over S such that $(s_1, s_2) \in \mathcal{B}$. ■

The relation \sim_{PEB} over MA models coincides with the relation $\sim_{\text{PTB,dis}}$ over $\mathbb{R}_{[0,1]}$ -ULTRAS models given in Def. 13. As a consequence, all the subsequent definitions and results in Sect. 5 also apply to $\mathbb{R}_{[0,1]}$ -ULTRAS models corresponding to MA models.

Theorem 6. Let $(S, A, \longrightarrow, \rightsquigarrow)$ be an MA and $\mathcal{U} = (S, A_{\mathcal{U}}, \longrightarrow_{\mathcal{U}})$ be the corresponding $\mathbb{R}_{[0,1]}$ -ULTRAS. For all $s_1, s_2 \in S$:

$$s_1 \sim_{\text{PEB}} s_2 \iff s_1 \sim_{\text{PTB,dis}} s_2 \quad \blacksquare$$

8 Discussion and Conclusions

In this paper, widely used timed models such as TA [1] (together with their underlying semantic model TLTS), PTA [12] (with their underlying PTLTS), and MA [7] have been put in a unifying view by encoding them in the ULTRAS framework [4] and by examining their bisimulation semantics [16, 20, 19, 7].

As immediate results of this work, we have been able to re-obtain the already existing timed bisimilarities and, most notably, to give new contributions. In particular, by naturally instantiating the ULTRAS general bisimilarity definition to the case of deterministically timed models – i.e., TLTS and TA – we have retrieved the same timed bisimilarity introduced in the literature (Thm. 1). Instead, when time is mixed with probability – i.e., for PTLTS, PTA, and MA models – we have found that the bisimilarities present in the literature, although expressible within the ULTRAS framework (Thms. 2 and 6), are different from the one that can be naturally obtained from ULTRAS. This has led us to introduce a new bisimilarity for those models (Def. 14 and Thm. 3), which we have called *group-by-group* and shown to be coarser than the original one (Thm. 4). Moreover, we have exhibited a modal logic characterization for the group-by-group bisimilarity by using an interval-based variant of the logic in [14] (Thm. 5), while the original bisimilarity needs a much more expressive logic [19].

The ULTRAS-based encodings permit also more general considerations about the studied models. Firstly, the transition relation of the ULTRAS corresponding to a TA is functional and based on \mathbb{B} , whilst in the case of a PTA/MA it is not a function (because internal nondeterminism cannot be mixed with probabilities in the target state distributions of transitions) and it is necessarily based on $\mathbb{R}_{[0,1]}$. This stresses the higher expressivity of PTA/MA compared to TA with regard to describing state reachability. Furthermore, it evidences a structural analogy between PTA and MA that has not been addressed so far in the literature.

Secondly, the quantitative information related to time in TA/PTA/MA can be made disappear to a large extent, while quantitative information related to probabilities in PTA/MA cannot be abstracted. This underlines an important difference between time and probability. Time elapses independent of the occurrence of events and hence its passage can be viewed as an event in its own, which can thus be represented like the other events. Probabilities, instead, are inherently associated with the occurrence of events and must therefore be explicitly represented as event attributes.

Indeed, in our encodings time passing has been represented through special actions that encompass the duration/rate of delays. A purely qualitative representation of time based on a single special action ϵ is also possible and was used, for instance, in the construction of the region/zone graph and in the notion of time-abstract bisimilarity [15]. This supports a compact description of the state space of the ULTRAS corresponding to a TA/PTA, which is uncountable while this is not necessarily the case for an MA. The reason is the inherent difference between deterministic time, which needs the concrete representation of all possible delays, and exponentially distributed time, for which a symbolic representation based on rates is sufficient thanks to the memoryless property.

A natural continuation of our work is to investigate trace and testing equivalences by applying their general definitions in [4] to the considered timed models.

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